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ORIGINAL ARTICLE

Powers of the Likelihood Ratio Test and the Correlation Test Using Empirical Bayes Estimates for Various Shrinkages in Population Pharmacokinetics

FP Combes^{1,2,3,4}, S Retout^{3,4}, N Frey⁴ and F Mentré^{1,2}

We compared the powers of the likelihood ratio test (LRT) and the Pearson correlation test (CT) from empirical Bayes estimates (EBEs) for various designs and shrinkages in the context of nonlinear mixed-effect modeling. Clinical trial simulation was performed with a simple pharmacokinetic model with various weight (WT) effects on volume (V). Data sets were analyzed with NONMEM 7.2 using first-order conditional estimation with interaction and stochastic approximation expectation maximization algorithms. The powers of LRT and CT in detecting the link between individual WT and V or clearance were computed to explore hidden or induced correlations, respectively. Although the different designs and variabilities could be related to the large shrinkage of the EBEs, type 1 errors and powers were similar in LRT and CT in all cases. Power was mostly influenced by covariate effect size and, to a lesser extent, by the informativeness of the design. Further studies with more models are needed. *CPT Pharmacometrics Syst. Pharmacol.* (2014) 3, e109; doi:10.1038/psp.2014.5; published online 9 April 2014

Population pharmacokinetics (PK) is increasingly used in drug development and is based on nonlinear mixed-effect models (NLMEMs).¹ Several software algorithms developed to estimate the parameters of these models have been compared, as by Plan *et al.*² The first and most popular software is NONMEM and, since version 7, several estimation algorithms have been available, such as first-order conditional estimation with interaction (FOCEI) and stochastic approximation expectation maximization (SAEM). Gibiansky *et al.*³ compared the performance of NONMEM estimation methods in simulated examples of a target-mediated drug disposition model using either default options or by designing the options to get the best possible results for each algorithm (“expert” options). They demonstrated the importance of the estimation options in the algorithm performance by comparing standard errors of NONMEM estimates with those predicted using PFIM 3.2 optimal design software.⁴ The SAEM algorithm provided estimates similar to those of FOCEI.

For a given model, when population parameters are estimated, individual parameters from individual observations can be estimated by a Bayesian approach using the maximum *a posteriori* method. If the data are from the individuals used to estimate population parameters, the same approach is used, but it is an empirical Bayes estimation. These individual parameter estimates are useful for investigating the influence of the individual’s baseline characteristics on the individual parameters.⁵

Population analysis allows the use of sparse sampling, but the sampling design influences the precision of population estimates.⁶ The informativeness of a data set in parameter estimation is a function of the number of subjects and of the number and timing of the samples.⁷ Optimal design methodology allows determination of the most informative

design with constraints. It computes a criterion, such as the D-optimality criterion, from the Fisher information matrix (M_e), which depends on the structural model, the parameter values, and the design.⁸

Thus, the design also greatly influences the precision of empirical Bayes estimates (EBEs). For a rich design, the *a posteriori* distributions of the individual random effects are centered on the true values with small standard deviations. When little information is available for each individual (sparse design), the means of these distributions regress towards the population mean with larger SDs. A formula from linear mixed-effect methodology has been used to predict this shrinkage of EBEs associated with a design.⁹ This shrinkage should be evaluated before conducting a clinical trial. Using a simulation study, we provide here a good prediction of shrinkage using the Bayesian Fisher information matrix (M_{BF})^{9,10}, avoiding the use of extensive simulations.

In a study of the impact of shrinkage on model building, Savic and Karlsson¹¹ show that covariate relationships may be masked or falsely induced and that the shape of the true relationship may be distorted when examined using a test of the correlation between the EBEs and the covariates. Savic and Karlsson¹¹ recommend as follows: “When shrinkage is high, other diagnostics and more direct population model estimation need to be employed in model building and evaluation.” They suggest more extensive use of the likelihood ratio test (LRT) test for covariate evaluation and selection when shrinkage is large, which is much more time consuming than selection from EBEs.

However, to our knowledge, no one has compared the power of LRT with the power of the correlation test (CT) with respect to design selection and its expected shrinkage. We therefore compared type 1 errors and power in detecting the effect of a continuous covariate using either the LRT or the

¹AME UMR 1137, INSERM, Paris, France; ²AME UMR 1137, Université Paris Diderot, Sorbonne Paris Cité, Paris, France; ³Institut Roche de Recherche et Médecine Translationnelle, Boulogne-Billancourt, France; ⁴Pharma Research and Early Development, Clinical Pharmacology, F. Hoffmann-La Roche Ltd, Basel, Switzerland. Correspondence: FP Combes (francois.combes@inserm.fr)

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CT based on EBEs according to various designs, along with various associated shrinkages.

Through an extensive Monte–Carlo simulation of a simple one-compartment PK model, we compared the performances of FOCEI and SAEM algorithms before evaluating the type 1 errors and powers of the tests to detect covariate influences on individual parameters. We also created several scenarios to vary the informativeness of the PK design and therefore the associated shrinkage.

RESULTS

Figure 1 summarizes the different clinical trial simulations performed.

Algorithm performance

Figure 2 presents, for each scenario and each design with $N = 500$, the boxplots of relative errors on parameters estimated using either FOCEI or SAEM with NONMEM 7.2. SAEM always provided more accurate estimates than FOCEI, except for ω_{ka} in scenario 2. Estimates with the FOCEI algorithm were often slightly biased, mainly for volume (V), clearance (CL), ω_{Vp} and ω_{CL} , and for residual error parameters. Bias was more marked for designs D2 and D3. Median values of relative errors using SAEM were less influenced by the design and were always close to 0%.

Considering that SAEM gave more accurate estimates than FOCEI, only SAEM power estimates are presented below. FOCEI power estimates are available in the **Supplementary Materials** online.

Prediction of shrinkage

Figure 3 shows predicted shrinkage vs. boxplots of observed shrinkage on V (left) and CL (right) for each design and each scenario without covariate effect. The simulated scenarios generated predicted shrinkage values that increased from D5 to D2. Confirming previous results,⁹ M_{BF} gave a good prediction of observed shrinkage. The boxplots were closely centered on the identity line, with small deviations for low shrinkages, for which there was a trend to predict lower shrinkages (but by less than or around 10% from median values of observed shrinkage).

Evaluation of tests

Figure 4 presents the boxplot of the error on β estimates for each scenario, design, and covariate effect. The covariate effect was always correctly estimated. When comparing the effect of the total number of subjects, the boxplots clearly show an increase in the SD of estimates with decrease in number of subjects.

Type 1 errors and the powers of tests between weight (WT) and V are presented in **Table 1** for all scenarios and designs and are illustrated in **Figure 5**. Type 1 error was similar for LRT and CT, even for high values of shrinkage, and in all cases, it was within the prediction interval of 3.65–6.35%. The power of LRT was equal to the power of CT in all scenarios, even with high shrinkage, the greatest difference being 2% for D5 with 200 subjects in scenario 1. **Figure 5a** illustrates how LRT and CT have very similar type 1 error and power.

The power was 95% for scenario 1 and 86% for scenario 2, with rich designs and a strong effect of WT. **Figure 5b** shows the lack of trend between shrinkage and power across scenarios and covariate effects. As expected, the power of tests was directly linked to the covariate effect. For both scenarios, a design modification led to a 25% increase in power when, for a given scenario and design, a change in covariate effect size induced a 50% increase.

When comparing $N = 500$ with D2 and $N = 200$ with D5, both with the same total number of samples, power was higher for D2 with a similar type 1 error.

When the covariate effect on CL was explored, type 1 error was similar for LRT and CT in all cases (**Table 1**). When no covariate effect was simulated on V, type 1 error remained within the range of the prediction interval, around 5%. Surprisingly, this type 1 error increased with the β value, especially in scenario 2. Type 1 errors were in all cases around 5% in scenario 1, except for D3 with $\beta = 0.5$ ($N = 500$, 6.4% for LRT) and for D5 with $\beta = 1$ ($N = 500$, 6.6% for CT). Considering scenario 2, the type 1 error computed for a strong covariate effect led to a significant increase in the type 1 error, for D2 (8.7% for LRT and 8.2% for CT), D3 (9.7% for CT and 9.6% for LRT), and D5 ($N = 500$, 6.9% for LRT). In this scenario, the increase in type 1 error is linked to higher correlation between individual V and CL. The median correlation was -0.25 for D2 and -0.23 for D3. Median correlation was -0.13 for scenario 2, D5, whereas for scenario 1, almost no correlation in the EBEs was found.

DISCUSSION

We have compared, for different scenarios and different PK sampling designs leading to various amounts of shrinkage, the type 1 error and power of two tests to detect the effect of a continuous covariate on a PK parameter: the LRT, which compares the log-likelihoods of two nested models; and a correlation test between the covariate and the EBEs.

Surprisingly, both tests showed the same power irrespective of the scenario or the design considered. Indeed, even if LRT is based on the fitting of two models to get the two likelihoods, it did not show greater power than a simple CT based on EBEs, even with high shrinkage. As a conclusion, because of its faster execution, we think that the CT should be used in a first screening of the relevant covariates, and then the selected covariates can be tested in a stepwise procedure to build the full covariate model using the LRT.

Savic and Karlsson¹¹ highlighted a possible issue when using the CT to screen covariates when there is high shrinkage in the EBEs and recommended a test that does not rely on EBEs. Our study shows that such a test, the LRT for instance, does not behave differently from the CT, whatever the shrinkage. Indeed, the loss of power associated with high shrinkage in CT has the same influence in the LRT and is linked with less information in the design. It also showed that the size of the covariate effect is the main factor linked to any covariate detection issue. Bertrand *et al.*¹² showed a similar link between power and covariate effect. To a lesser extent, the information in the design also has an impact on the power, which decreases when the number of sampling

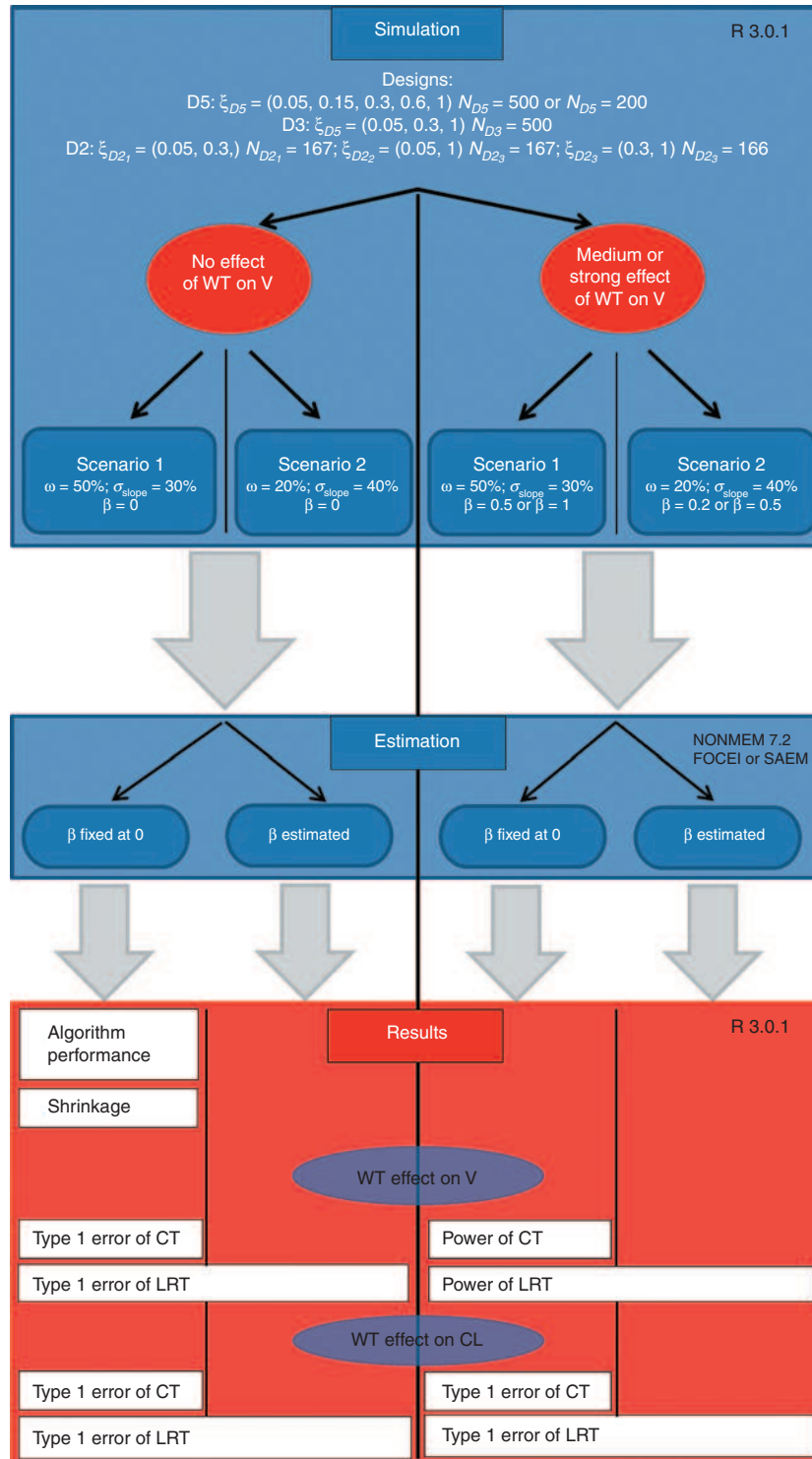


Figure 1 Global scheme of the clinical trial simulations. CL, clearance; CT, correlation test; FOCEI, first-order conditional estimation with interaction; LRT, likelihood ratio test; SAEM, stochastic approximation expectation maximization; V, volume; WT, weight.

times per subject decreases. Furthermore, when comparing the two designs with the same number of samples, power was found to be greater for 500 subjects (D2) than for 200 (D5), though the latter has lower shrinkage (Table 1, with $\beta = 1$, with WT effect on V). This decrease in power for 200 subjects can be explained by the very challenging conditions we

used to simulate the covariate effect (rather small variance of WT and rather small covariate effect). These results are in accordance with the loss of power associated with decreased number of subjects reported by Liu *et al.*¹³ and Bertrand *et al.*¹⁴ Nevertheless, even if the LRT was not significant, the covariate effect, β , was always correctly estimated.

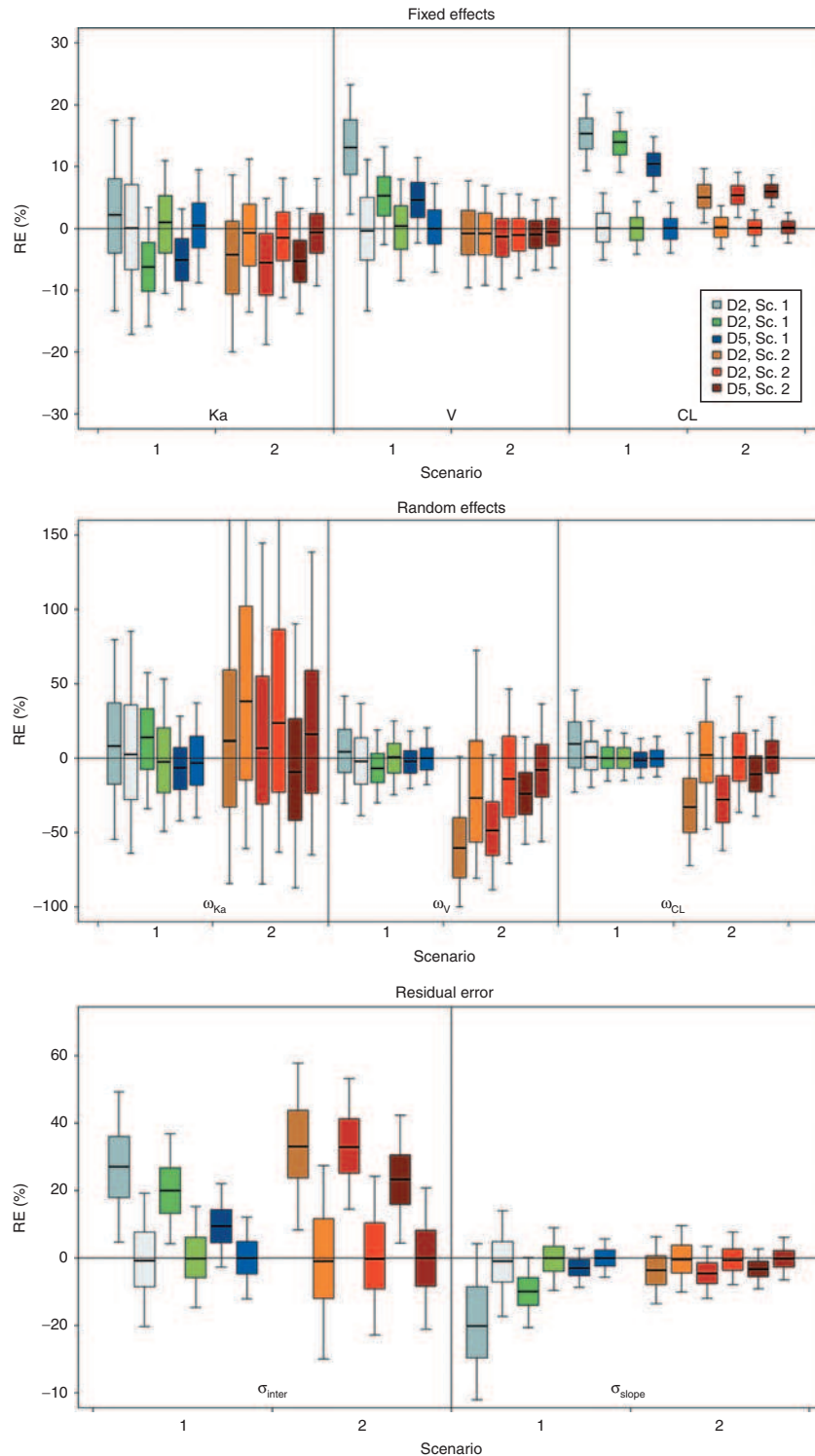


Figure 2 Boxplot of relative error (RE; %) on estimated fixed effects (top) without covariate effect, random effects (middle), and residual error parameters (bottom) according to scenario 1 or 2, the design, and the estimation algorithms. Boxplots represent the median, quartiles, and 5–95% percentiles. Colors stand for the design and the scenario. For the same color, the dark areas represent the first-order conditional estimation with interaction algorithm and the pale areas denote the stochastic approximation expectation maximization algorithm. Sc., scenario.

Considering the induction of correlation due to high shrinkage, a slight inflation of type 1 error in scenario 2 was found. This inflation could be explained by the EBE correlation between V and CL . The influence of design on EBE

correlation should be investigated in future work. Further work is also needed to explore the influence of design on a full covariate modeling process, with several covariates influencing the parameters.

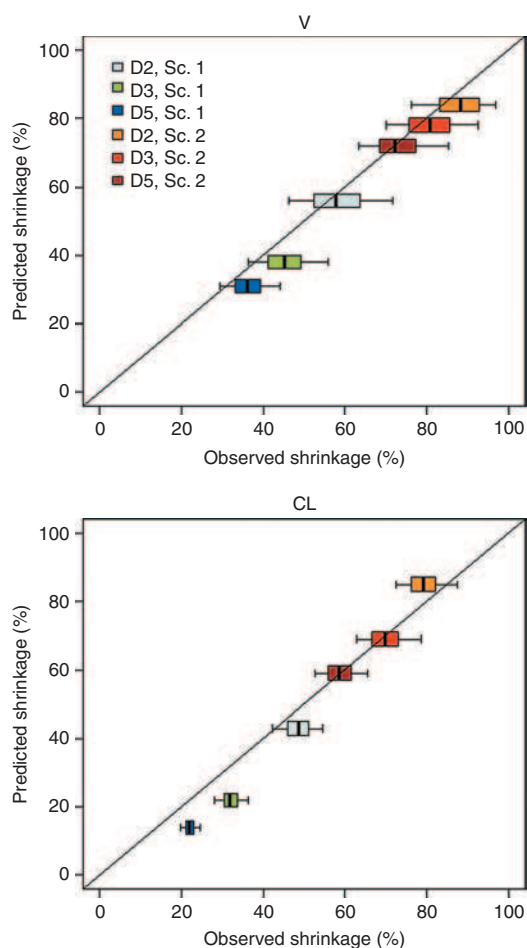


Figure 3 Predicted shrinkage (%) value vs. boxplot of observed shrinkage (%) with the stochastic approximation expectation maximization algorithm for the 1,000 replicates without covariate effect, for parameters volume (V) and clearance (CL), each design, and scenarios 1 or 2. Colors stand for the design and the scenario. Sc., scenario.

This simulation study also confirms the good prediction of shrinkage using the Bayesian Fisher information matrix, as already shown in ref. 9, when planning clinical studies. This could be helpful in the design of population studies wherein individual estimation of individual parameters with small shrinkage is needed.

As expected, our investigations showed that the SAEM algorithm reliably and accurately estimates population parameters, even for sparse designs. FOCEI gave surprisingly biased results for such a simple model even with rather informative designs. This bias could be explained by the rather large residual error used in our simulations, inducing bias in the linearization during FOCEI.¹⁵ This result is not unusual considering previous comparisons of FOCEI and SAEM for continuous data. Girard and Mentré reported that methods without likelihood approximations, such as SAEM (using a version that later became MONOLIX (MOdèles Non Linéaires à effets mixtes)) perform better than first order or FOCEI.¹⁶ Using a previous version of NONMEM (5 and 6 β), Dartois *et al.*¹⁷ reported very good estimation of parameters despite some discrepancies in residual error estimates and

recommended the use of exact methods such as SAEM instead of FOCEI. At the time of these two studies, SAEM was not implemented in NONMEM. In addition, Ueckert *et al.*¹⁸ and Johansson *et al.*¹⁹ showed the same loss of “robustness” and “precision” of FOCEI compared with SAEM, for continuous data, especially when mu-modeling is used for SAEM in NONMEM 7. Finally, Plan *et al.*² compared various algorithms using NONMEM, Statistical Analysis System, MONOLIX, and R and found that FOCEI was in some cases more biased than SAEM, especially for sparse designs, along with issues related to the convergence of the algorithm.

Results for the power of CT and LRT for data sets analyzed using the FOCEI algorithm can be found in the **Supplementary Materials** online for designs D2 and D5 with $N = 500$ subjects. Despite some rather biased estimations of population parameters with FOCEI, there was no bias in the estimation of β . Type 1 error and power were similar for FOCEI and SAEM, with only a slight inflation of the type 1 error in scenario 2 for sparse designs. Our selection of the NONMEM 7.2 algorithm and options relied on advice and results presented in ref. 3. Further work is needed to explore the influence of the algorithm options (number of samples and iterations for Monte Carlo importance sampling (IMP) algorithm) on the likelihood computation.

Larger residual error variances than those used in our study may be rather unusual in the field of pharmacometrics. We performed our study for a wide range of shrinkages, and the tests performed similarly whether the generated shrinkage was low or high (Table 1). The use of different error models and the magnitude of those errors could affect the amount of generated shrinkage.^{9,20} A high residual error would obviously decrease the power of the test. Further work is needed on the extent to which similarities between CT and LRT are influenced by the level and form of residual error.

In our simulation study, we used a rather narrow distribution of covariates and challenging medium covariate effects. This was done on purpose because, for greater covariate distribution and larger covariate effect, the power was very high and we could not investigate the influence of other factors. We studied covariate effects using a power function along with an exponential form of random effects. These forms are the most used in population PK modeling. Studies using other forms of random effects and covariate models are therefore needed.

We only explored the power of covariate detection using LRT and CT with different designs and variabilities. LRT and CT are still the most used in population PK. Future work should focus on other covariate selection methods, such as Generalized Additive Modeling (GAM) analysis²¹ and Least Absolute Shrinkage and Selection Operator (LASSO),²² but these are mainly used when several covariates are considered. Furthermore, the impact of structural model misspecification could be evaluated along with the effect of design on the covariate selection process.²³

The main objective of our work was to compare the performance of CT and LRT for different shrinkages. Although we used a rather simple model, the outcomes provided important information in line with the findings of Savic and Karlsson,¹¹ and the screening of covariates was done with CT instead of the more time-consuming LRT. The next step will be to confirm our results with a more complex model, such as a target-mediated drug disposition model, which involves the use of differential

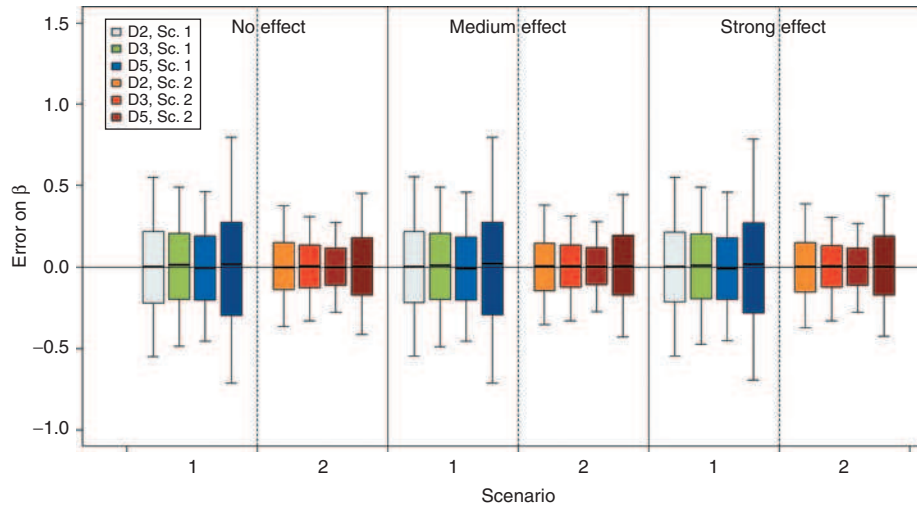


Figure 4 Boxplot of error on the estimated β value with the stochastic approximation expectation maximization algorithm and for a covariate effect on volume (V), according to scenarios 1 or 2, the design, the simulated covariate effect value, and the number of subjects. Boxplots represent the median, quartiles, and 5–95% percentiles. Colors stand for the design and the scenario. For D5, pale and dark areas are used, respectively, for designs with 500 and 200 subjects. Sc., scenario.

Table 1 Type 1 error (% , $\beta = 0$), power (% , $\beta \neq 0$) of LRT and CT tests for covariate effect, and predicted shrinkage on V and CL for all scenarios, simulated covariate effect levels, and designs

n	N	Test	WT on V									WT on CL						
			Scenario 1			Scenario 2			Scenario 1			Scenario 2						
			$\omega = 50\%$; $\sigma_{\text{slope}} = 30\%$			$\omega = 20\%$; $\sigma_{\text{slope}} = 40\%$			$\omega = 50\%$; $\sigma_{\text{slope}} = 30\%$			$\omega = 20\%$; $\sigma_{\text{slope}} = 40\%$						
			Predicted shrinkage	Power (%)		Predicted shrinkage	Power (%)		Predicted shrinkage	Power (%)		Predicted shrinkage	Power (%)					
β	β	β		β	β		β											
2	500	LRT	56	3.8	29.7	84.8	84	4.2	14.3	59.4	43	4.7	4.6	4.6	85	5.5	6.2	8.7
		CT		3.9	29	83.6		4.0	14.3	60.1		4.5	4.5	4.5		4.8	5.8	8.2
3	500	LRT	37	4.6	38.3	91.6	78	4.6	18.6	76.2	22	5.8	6.4	6.3	69	5.6	6.8	9.6
		CT		4.3	37.7	90.6		4.9	18.0	75.2		6.1	6.1	6.3		5.4	6.1	9.7
5	500	LRT	31	4.8	43.5	95.4	72	5.0	25.0	85.7	14	6.1	5.6	5.8	59	4.8	4.7	6.9
		CT		4.7	43.4	93.9		5.0	24.0	84.8		6.0	5.8	6.6		4.3	4.9	6.3
5	200	LRT	31	5.7	20.5	64.1	72	4.7	11.7	47.7	14	5.6	5.3	5.0	59	5.2	5.3	6.1
		CT		5.9	19.6	62.1		4.8	11.6	47.4		5.1	5.2	5.2		5.0	4.9	5.6

Population parameters were estimated using the SAEM algorithm. Type 1 errors outside the prediction interval are written in bold.

CL, clearance; CT, correlation test; LRT, likelihood ratio test; SAEM, stochastic approximation expectation maximization; V, volume; WT, weight.

equations and for which use of CT should be all the more beneficial in a model development process, considering the runtime that such a system requires for parameter estimation.

METHODS

Models and notations

For a given individual, let y_i be the vector of n observed concentrations at n sampling times $\xi_i = \{t_{i,1}, \dots, t_{i,n}\}$ for subject i and f be the known function describing the PK model. So, y_i was assumed to be modeled as follows:

$$y_i = f(\theta_i, \xi_i) + \varepsilon_i \quad (1)$$

where θ_i is the p vector of individual PK parameters, $\theta_i = (\theta_{i,1}, \dots, \theta_{i,p})^T$; ε_i is the random error, following a normal distribution with zero mean and variance $\Sigma(\theta_i, \xi_i)$. Here, $\Sigma(\theta_i, \xi_i)$ is defined as the variance matrix of a combined error model

with an additive component σ_{inter} and a proportional one σ_{slope} ; hence, $\Sigma(\theta_i, \xi_i) = \text{diag}((\sigma_{\text{inter}} + \sigma_{\text{slope}} f(\theta_i, \xi_i))^2)$.

Individual parameters θ_i are defined as $\theta_i = g(\theta, \eta_i)$ where θ is the vector of p fixed effects and η_i is the vector of p individual random effects $\eta_i = (\eta_{i,1}, \dots, \eta_{i,p})^T$. Random effects η_i follow a normal distribution with zero mean and variance Ω . For Ω , a diagonal $p \times p$ matrix of variances of random effects $\Omega = \text{diag}(\omega_1^2, \dots, \omega_p^2)$ was assumed. For $g(\theta, \eta_i)$, an exponential model, where $g(\theta_k, \eta_{i,k}) = \theta_k e^{\eta_{i,k}}$ was considered, $k = \{1, \dots, p\}$. The vector Ψ of population parameters is composed of $\{\theta_1, \dots, \theta_p, \omega_1^2, \dots, \omega_p^2, \sigma_{\text{inter}}^2, \sigma_{\text{slope}}^2\}$.

In PK modeling, population parameters are estimated by the method of maximum likelihood. Individual parameters are estimated by a Bayesian approach using the maximum *a posteriori* as follows:

$$\hat{\eta}_i = \text{argmax}(p(\eta_i | y_i)) \quad (2)$$

where $p(\eta_i|y_i)$ is the probability distribution of η_i given y_i , which can be expressed using the Bayes theorem as shown below:

$$p(\eta_i | y_i) = \frac{p(y_i | \eta_i)p(\eta_i)}{p(y_i)}. \quad (3)$$

To estimate $\hat{\eta}_i$ by maximum *a posteriori* is equivalent to minimizing, with respect to η_i :

$$-2 \times (\ln(p(y_i | \eta_i)) + \ln(p(\eta_i))) \quad (4)$$

This is equal to

$$\sum_{j=1}^n \left(\frac{(y_{i,j} - f(g(\theta, \eta_i), t_{i,j}))^2}{(\sigma_{\text{inter}} + \sigma_{\text{slope}} f(g(\theta, \eta_i), t_{i,j}))^2} + \ln(\sigma_{\text{inter}} + \sigma_{\text{slope}} f(g(\theta, \eta_i), t_{i,j}))^2 \right) + \sum_{k=1}^p \frac{\eta_{i,k}^2}{\omega_k^2}. \quad (5)$$

PK model of the simulation study

A simulated example involving a one-compartment model with a single oral administration was used. The three parameters are the absorption rate (ka), the apparent volume of distribution (V), and the apparent clearance (CL). For a given dose D , the prediction at time $t_{i,j}$ is shown below:

$$f(\theta, t_{i,j}) = \frac{D \times ka_i}{V_i \times \left(ka_i - \frac{CL_i}{V_i}\right)} \left(e^{-\frac{CL_i}{V_i} \times t_{i,j}} - e^{-ka_i \times t_{i,j}} \right) \quad (6)$$

We chose $\theta_{ka} = 10$, $\theta_V = 0.2$, and $\theta_{CL} = 0.5$ with a dose $D = 1$. As this model is theoretical, we did not consider any specific units. The PK profile for these typical values of parameters is shown in **Figure 6**. To explore the influence of shrinkage in various situations, two scenarios were considered: for scenario 1, $\omega = 50\%$ for each parameter and $\sigma_{\text{slope}} = 30\%$; for scenario 2, $\omega = 20\%$ and $\sigma_{\text{slope}} = 40\%$. Σ_{inter} was set to 0.15 in both cases, which is small with respect to the range of concentrations covered by the PK model (see **Figure 6** for the mean concentration–time course profile).

Study design

$N = 500$ subjects were simulated using three designs. First, a design with five samples (D5) per subject, $\xi_{D5} = \{0.05, 0.15, 0.3, 0.6, 1\}$, was simulated and is presented in **Figure 6**. The simulation code is provided in the **Supplementary Materials** online. For these sampling times, the most informative design with three samples (D3) was then determined using a D-optimality approach: $\xi_{D2} = \{0.05, 0.3, 1\}$. Finally, from ξ_{D3} , a two-sample design (D2) with three groups of one-third of the N subjects each was created: $\xi_{D2_1} = \{0.05, 0.3\}$ ($N_{D2_1} = 167$ subjects), $\xi_{D2_2} = \{0.05, 1\}$ ($N_{D2_2} = 167$ subjects), and $\xi_{D2_3} = \{0.3, 1\}$ ($N_{D2_3} = 166$ subjects). Design D5 was also evaluated with $N = 200$ subjects, which corresponds to the same total number of observations as D2 with 500 subjects.

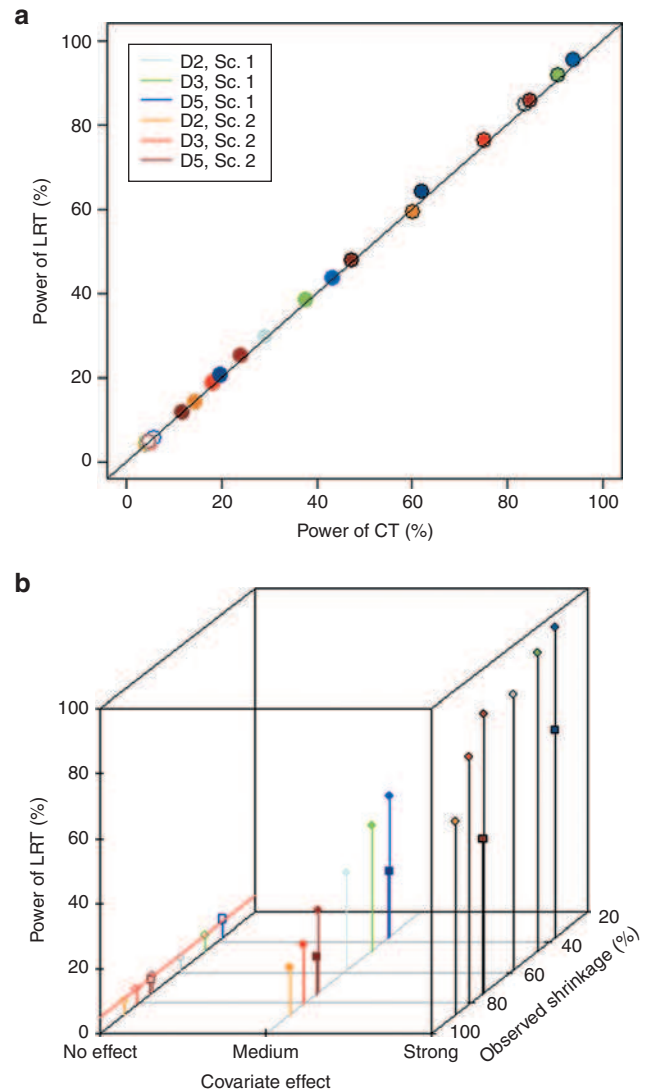


Figure 5 Power of likelihood ratio test (LRT) between weight (WT) and volume (V) (%), for all scenarios and designs (estimation with stochastic approximation expectation maximization algorithm) vs. (a) correlation test (CT; %; the black line represents the identity line). (b) Observed shrinkage on V (%) and covariate effect. Colors stand for the design and the scenario. Covariate effect is expressed by the background and colors: no effect with a colored line around dots, medium effect with fully colored dots, and strong covariate effect with black line around a colored dot. For D5, pale and dark areas are used respectively for designs with 500 and 200 subjects. Sc., scenario.

Evaluation of estimation

In the first step, $R = 1,000$ data sets were simulated without covariate effect for each design (D2, D3, and D5 with $N = 500$) and each scenario. Each data set was analyzed using NONMEM 7.2²⁴ with FOCEI and with SAEM to explore algorithm performances. Expert options inspired by Gibiansky *et al.*³ were used for the setting of the SAEM algorithm (INTERACTION NBURN=15000 ISAMPLE=3 NITER=5000 SIGL=8 CTYPE=3 CINTERVAL=100). NONMEM codes are available in the **Supplementary Materials** online. Relative errors of estimations of population parameters, (in percentage), were computed for each component as in Eq. 7:

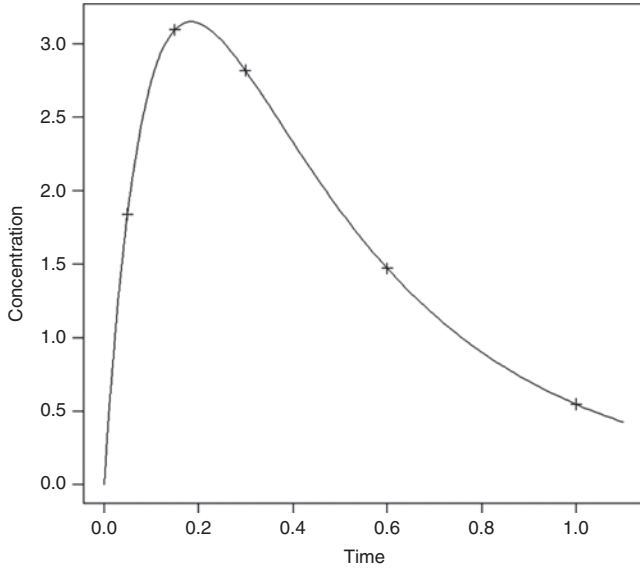


Figure 6 Pharmacokinetic (PK) profile for the mean PK parameters of the simulated example with design D5.

$$RE_{r,k} = \frac{\hat{\Psi}_{r,k} - \Psi_k}{\Psi_k} \times 100 \quad (7)$$

where $\hat{\Psi}_{r,k}$ is the k^{th} component of the vector of the estimated population parameter for the r^{th} data set and Ψ_k is the value used in the simulation.

Prediction of shrinkage

As in the study by Combes *et al.*,⁹ the predicted shrinkage is computed as $I - W(\xi)$ where

$$W(\xi) = I - M_{BF}(\xi)^{-1} \Omega^{-1},$$

and I is the identity matrix, such that :

$$I - W(\xi) = M_{BF}(\xi)^{-1} \Omega^{-1} \quad (8)$$

M_{BF} can be approximated by a first-order linearization of the model²⁵:

$$M_{BF}(\xi)^\infty = H^T F(\theta, \xi)^T \Sigma(\theta, \xi)^{-1} F(\theta, \xi) H + \Omega^{-1} \quad (9)$$

where $H = \text{diag}(\theta_1, \dots, \theta_p)$ and $F(\theta, \xi) = \frac{\partial f(\theta, \xi)}{\partial \theta^T}$. As Ω is diagonal, the diagonal elements of $I - W$, given in the Eq. 8, represent the ratio of the predicted variance of estimation using a Bayesian estimation and the *a priori* variance. When M_{BF}^{-1} is close to Ω (no information for the individual), $I - W$ is close to I . In that case, shrinkage is expected to be high, close to 100%.

The selected designs and scenarios were chosen to lead to a wide range of predicted shrinkages on V and CL , between 31 and 84% for volume and between 14 to 85% for clearance (see results in [Table 1](#)).

For each data set r , the observed shrinkage of each component k was computed as follows:

$$\text{Sh}_{k,r} = 1 - \frac{\text{var}(\hat{\eta}_{k,r})}{\hat{\omega}_{k,r}^2} \times 100 \quad (10)$$

The distribution of the 1,000 observed shrinkages from the 1,000 data sets was compared with the predicted shrinkage.

Evaluation of tests for covariate detection

We then considered a covariate model describing the influence of the weight (WT) on volume using a power function:

$$\theta_{v,i} = \theta_v \left(\frac{WT_i}{WT} \right)^\beta e^{\eta_{v,i}} \quad (11)$$

We assumed a log-normal distribution of WT with a median $\overline{WT} = 70$ kg and a coefficient of variation of 10% (quantiles 2.5–97.5%: 57–85 kg). We considered this distribution range so as to avoid a very large distribution, which would contribute to very powerful covariate detection whatever the test and design. Designs involving 500 subjects led to powers close to 100% for LRT and CT, whatever the number of samples per individual.

$R = 1,000$ data sets for each design and scenario were simulated. For scenario 1, we first considered a case close to an allometric effect with $\beta = 1$. We then considered a smaller value of that effect $\beta = 0.5$ (medium effect) and no effect $\beta = 0$. Regarding scenario 2, as smaller variances were considered, we reduced the values of β to generate a strong covariate effect ($\beta = 0.5$), a medium effect ($\beta = 0.2$), or no effect ($\beta = 0$).

Using these simulations, we evaluated the properties of two tests in detecting the effect of the weight (WT) on volume (V). First, the LRT, which compares the log-likelihoods of the two nested models (with β fixed to 0 or β on V estimated), was considered significant when the difference in $-2 \times \log$ -likelihood was greater than 3.84, (the 95% limit of a χ^2 distribution with one degree of freedom). The second test was a parametric correlation Pearson test between EBEs of volume from a population analysis with no covariate in the model and weights.

Data sets were analyzed with the SAEM algorithm for population estimation. Likelihood was then computed by importance sampling (algorithm IMP in NONMEM 7.2 with 10 iterations and 3,000 samples).

We first estimated the covariate effect by exploring the error on the estimated β values as the estimated value of β minus the true value used for simulation.

Type 1 error α was then computed as the percentage of significant tests (P value < 0.05) in the R replicates simulated assuming a null hypothesis H_0 ($\beta = 0$). We computed the 95% prediction interval for a binomial distribution with a probability of 0.05 and 1,000 replicates using the 2.5 and 97.5% percentiles. The prediction interval was 3.65–6.35%. For a test with $\alpha = 0.05$, we expect the estimated type 1 error to lie within this interval. The power of tests was computed as the percentage of significant tests in the R replicates simulated assuming the alternative hypothesis H_1 ($\beta \neq 0$).

Finally, in order to evaluate the risk of induction of covariate effects because of shrinkage,¹¹ the same tests were evaluated for the relationship between WT and CL , although no WT effect was simulated in CL . We computed type 1 error for CT and LRT in the effect of WT on CL . Results (tests, predicted and observed shrinkage) were computed using R 3.0.1.

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Study Highlights

WHAT IS THE CURRENT KNOWLEDGE ON THE TOPIC?

✓ In population analysis, tests based on correlation (CT) between empirical Bayes estimates (EBEs) and covariates can be misleading when those estimates are greatly shrunk. Tests relying on EBEs are therefore not recommended for high shrinkage (Savic and Karlsson). There is no study of the extent to which the loss of power in the likelihood ratio test (LRT) is also associated with sparser design.

WHAT QUESTION DID THIS STUDY ADDRESS?

✓ This study compares the performances of the LRT and the CT in detecting a continuous covariate effect, according to different covariate effect sizes and designs.

WHAT THIS STUDY ADDS TO OUR KNOWLEDGE

✓ This study shows that for a simple PK model, LRT and CT perform similarly, whatever the covariate effect size and design, even in the case of high shrinkage.

HOW THIS MIGHT CHANGE CLINICAL PHARMACOLOGY AND THERAPEUTICS

✓ If the results are confirmed with more complex models, CT should be used to screen covariates, without any loss of power compared with LRT and with a faster execution time.

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